深圳市星科创科技有限公司
Shenzhen XingKeChuang Technology Co., Ltd.

Instruction Manual of Laser Ranging Sensor
XKC-KL200-2M-UART

table of contents

1st. Overview

XKC-KL200-2M-UART is a smart non-contact switch, laser ranging sensor with UART serial port, drive output. The sensor uses the principle of laser diffuse reflection on objects: when a person or an object enters the sensing area set by the sensor, the sensor outputs a signal and can accurately output the distance; when the person or object leaves the sensing area, the sensor turns off the output.

2nd.Product Features

1. Strong anti-interference ability.
2. Intelligent induction non-contact switch, safe and hygienic.
3. The sensing angle is small.
4. Small size, easy to install.
5. A variety of output methods, easy to use.
6. Not affected by the surface color of the object.
7. In an indoor environment, the real-time measurement distance can reach 2 meters.
8. Multi-layer filter cover, the sensor is more stable.

3rd. Scope of application

1. Intelligent induction sanitary ware.
2. Home security.
3. Intelligent detection and intelligent control.
4. Robot obstacle recognition.
5. Real-time display of distance.
6. Faucet sensor, automatic flushing of toilet and toilet, automatic hand dryer, anti-theft device, automatic doorbell, stairway sensor, TV close-up TV reminder, automatic door, advertising light box, automatic trash can.

4th. Technical Parameters

project name	Parameters
Operating Voltage	DC 5~24V
Sensing distance	In the effective distance (10mm~2000mm), calibration test in various modes, various performance should meet the requirements, and the distance of 1000mm can be measured in the sun.
Sensing accuracy	±4%　(Within 10mm~2000mm)
wavelength	940 nm Laser transmitter
Sensing angle	Transmit 35 degrees, receive 25 degrees。
Short circuit protection	When more than 1A, the output is turned off
Specification	24*24　(Main shell)
Load current	300mA

Working current	15mA
Working temperature	-20～65℃
storage temperature	-20～85℃
Line length	30cm （±10MM）(Bulk can be customized)
Material	shell: PC-V0 fireproof material
output method	UART serial port

User Calibration Guide

The factory default response distance of the laser switch is 2000mm, and the default response distance can be specified according to user requirements.

Or users can calibrate themselves, the calibration steps are as follows:

1. Fix the sensor and set the distance between the measured object and the sensor within the effective distance (10mm~2000mm).

2. Long press the button for 3 seconds, the LED starts to flash slowly (1s/1s), indicating the start of calibration.

3. Wait for about 3 seconds, the calibration will automatically enter the action state after the calibration is completed, and the LED will always be on, indicating that the calibration is successful.

4. If the calibration distance exceeds the range 10-2000mm), it will flash quickly (50ms/50ms) for 2 seconds and then go out.

5. If an object is detected and the calibration is not completed, it will keep flashing.

(The distance changes within 3 seconds, the object has total transmission, all mirror reflection, unstable fixation... all may lead to unsuccessful calibration).

6. If the object is not detected, the calibration has not been completed, and the light will be off after 10 seconds.

Baud rate configuration table：	
Serial number	Baud rate
0	2400
1	4800
2	9600
3	14400
4	19200
5	38400
6	56000
7	57600
8	115200

| 9 | 128000 |

UART serial port output: laser switches (except XKC-KL200-2M-V), all with UART configuration function, users can configure related parameters through UART, or specify factory default configuration values. The default configuration values   of Xingkechuang are as follows.

Laser switch UART parameter configuration table:

Configuration item	Defaults	instruction
Baud rate	2=9600bps	0-9,2400bps-128000bps (see the baud rate configuration table for details)
Device address	0	0-65534 (65535 is the broadcast address)
Calibration distance value	100	10-2000 (10-2000mm)
Upload mode	1=Manual query	0=auto upload, 1=manual query
Upload interval	10	Value range 1-100 (corresponding to 100ms-10s)
LED mode	0=lights up when there is induction	0=light on when there is induction, 1=off when there is induction, 2=normally off, 3=normally on
Relay mode	0=Start when there is induction	0=start when there is induction, 1=close when there is induction
Line output mode	0=Relay mode	0=relay mode, 1=UART mode

5th. Laser switch LED indicator

Phenomenon	LED indication	Flash parameters (on/off)
Output short circuit	Flash	50ms/50ms
Product failure	Pulse flash	10ms/2S
Calibrating	Slow flashing	1S/1S
Calibration error	Flash	50ms/50ms
Object detected	Chang Liang	
No object detected	Always off	

6th. wiring diagram of various models

Simplified schematic diagram of UART serial port output wiring principle

XKC-KL200-UART Serial signal output principle and wiring method

Brown VCC
yellow OUT
blue GND
black RXD

Wiring port definition

1. Power positive brown
2. Signal output yellow
3. Power negative blue
4. Signal reception black

Terminal wiring sequence

Brown VCC DC5~24V
VCC 3-5V
R

yellow TXD — RXD — R 1K

sensor

blue GND Power negative — GND

black RXD(Hanging) — TXD

control system Device
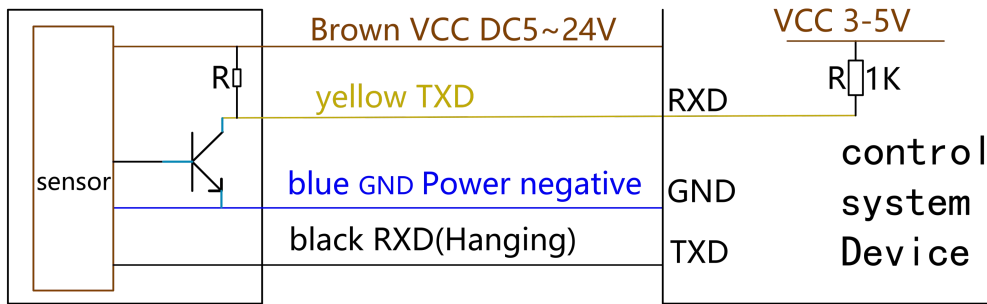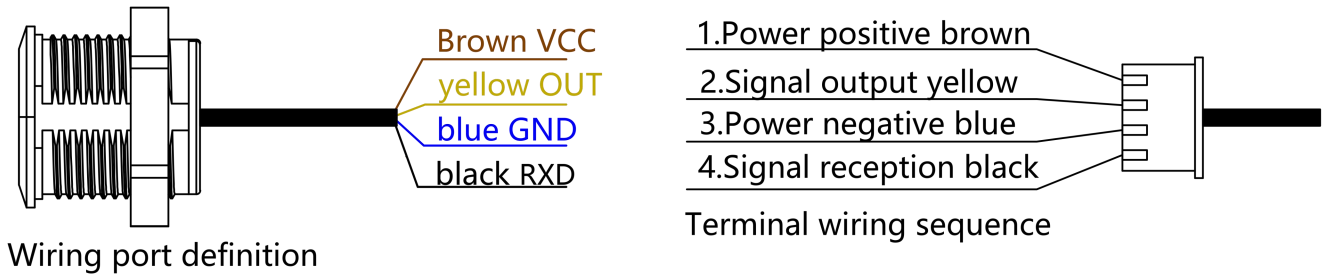
UART serial port signal output: the wiring method to connect to the controller or MCU
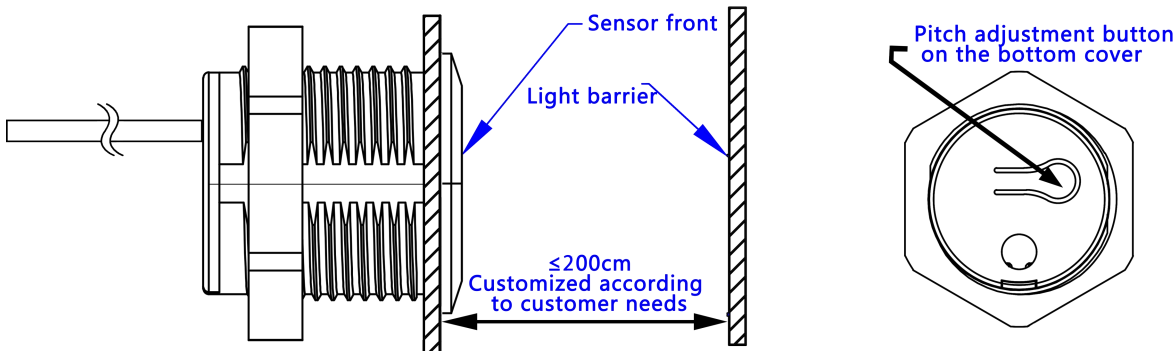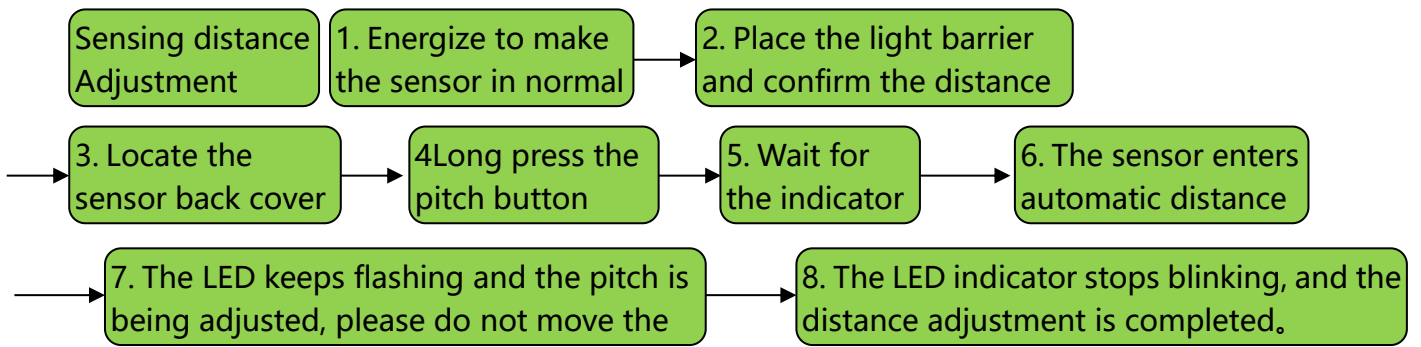

7th. Sensing distance adjustment

1. Place a piece of kraft cardboard about 80cm * 80cm in front of the sensor 200cm (set according to user needs within the range of 10~200cm).
2. The sensor is powered on.
3. Locate the button on the back cover of the sensor, and then press and hold the button.
4. After the indicator light is on for about 1 to 2 seconds, release the button to enter the automatic sensing distance adjustment mode. The sensor and the cardboard should not move, and there should be no obstructions between them. After waiting for about 10 seconds, the indicator light stops flashing and automatically saves the data; it automatically returns to the normal working mode. The pitch adjustment is complete.

Sensor front

Light barrier

Pitch adjustment button on the bottom cover

≤200cm
Customized according to customer needs

Sensing distance adjustment process

Sensing distance Adjustment	1. Energize to make the sensor in normal	2. Place the light barrier and confirm the distance

3. Locate the sensor back cover	4Long press the pitch button	5. Wait for the indicator	6. The sensor enters automatic distance

7. The LED keeps flashing and the pitch is being adjusted, please do not move the	8. The LED indicator stops blinking, and the distance adjustment is completed。

8th. Dimensions and physical objects

Phone: 86-0755-33523599   FAX: 86-0755-33515410   URL: http://www.sz-xkc.com
Address: 11th Floor, No. 48, Xinyu Road, Xinqiao Community, Xinqiao Street, Baoan District, Shenzhen
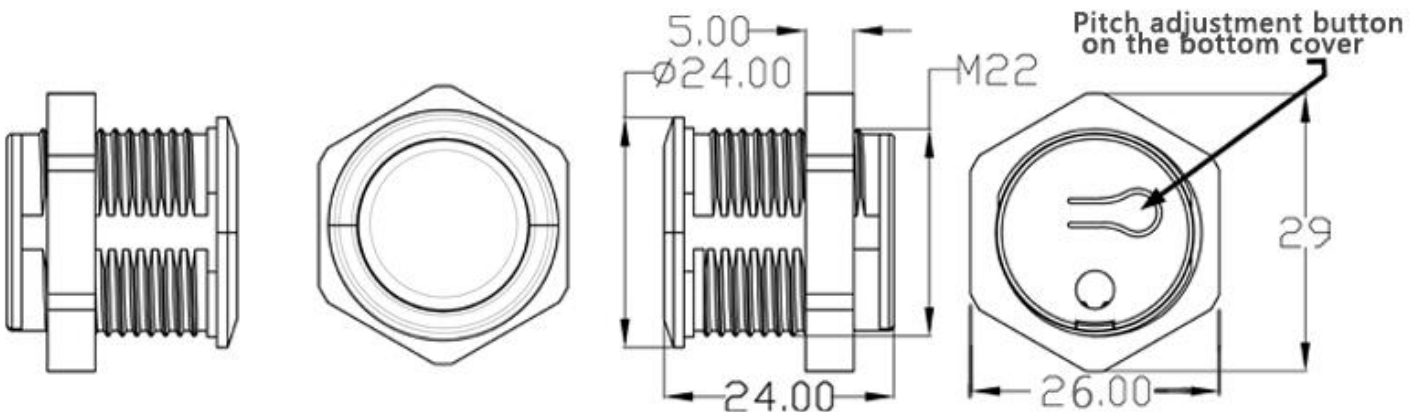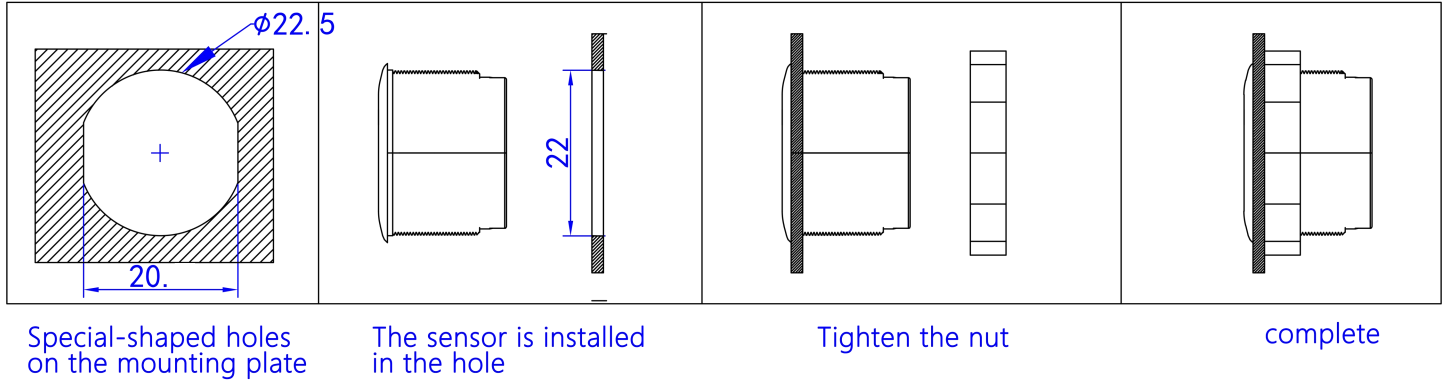
9th. installation method

Open a special-shaped hole on the panel where the sensor needs to be installed, install the sensor into the hole from the front of the panel, and tighten the nut behind the sensor.。

| Special-shaped holes on the mounting plate | The sensor is installed in the hole | Tighten the nut | complete |

10th. Distance and Object Size Relationship

Minimum diameter range = distance * 0.4666 (mm)
As shown in the figure: when the distance between the sensor and the measured object is 2 meters,Then the size of the object should not be less than 934mm;
when the distance between the sensor and the measured object is 1 meters,
Then the size of the object should not be lower than 467mm.
Note:
The laser receiving angle is 25 degrees,
and the tangent function value of 25 degrees is 0.4666

Φ0mm Φ233mm Φ467mm Φ700mm Φ934mm

0meters 0.5meters 1meters 1.5meters 2meters

distance

Minimum diameter range
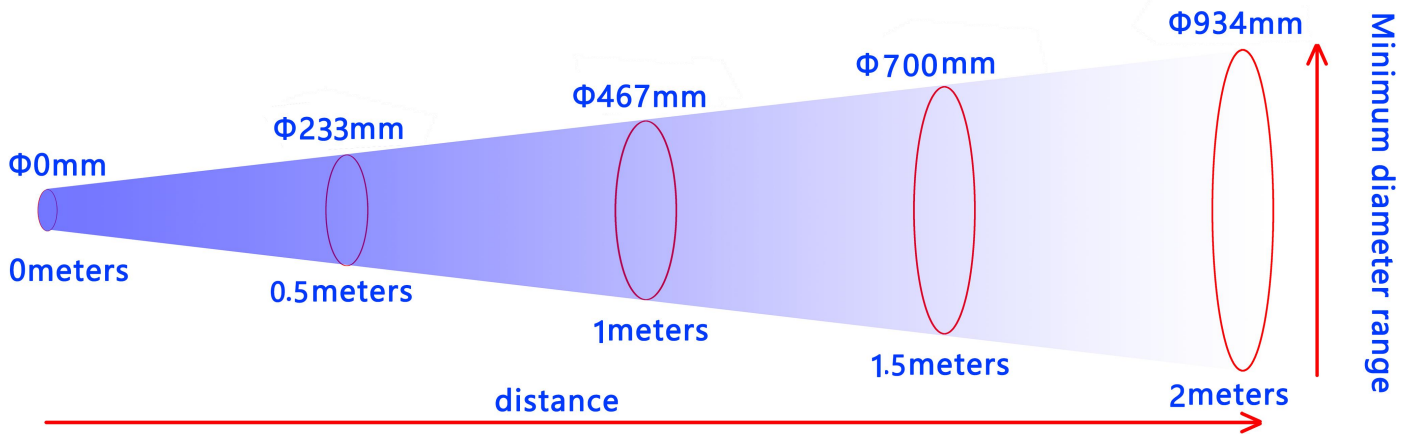
11th. letter of agreement

1.1 The hardware adopts uart.

Brown (VCC), yellow (signal output), blue (GND), black (RXD)

Except XKC-KL200-2M-V, all our laser switch products can be used for UART application, please pay attention to user needs:

1. Power supply 5~24V

2. Connect a pull-up resistor of about 1K between the customer's MCU power supply and the OUTPUT

(yellow wire).

1.2 The default configuration of the serial port:

Baud rate: 9600

Data bits: 8

Check Digit: None

Stop bit: 1

1.3 Data format: Hexadecimal:

Data Format	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B2)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR)
Send instructions	62	32	09	00	FF	FF	01	00	XOR
General command ACK	62	32	09	00	00	00	00	66	XOR
Read current configuration (Hex) ACK	01	02	03	04		05	6~27	28	29
	62	31	1D	00		00	22 bytes of configuration data	66	XOR
Read current configuration (string)	Configuration string								

1. ASCII command code:

b9 Restore factory settings

b0 configure baud rate

b1 Read current configuration information

b2 Configure 485 address

b3 Read data or upload data automatically

b4 Configure upload data mode

b5 Configure the active upload time interval

b7 Configure LED mode

b8 Configure the relay mode

a0 Configure line mode

a1 Configure response speed

2. Data length: the entire length from the first byte (inclusive) of the command to the check byte (inclusive)

3.Slave address: 0x0000-0xfffe

4. Data: Upstream sensor detection data, configuration data or downstream configuration data

Read current configuration: 22 bytes of configuration data or string (see Read Configuration Instructions for details)

Other instructions: two bytes of data

5. Response: Command is 0x00, response is 0x66
6.Check: 8-bit XOR check

1.4 Function instructions

Restore Factory	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B2)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR)
Restore Factory	62	39	09	FF	FF	FF	FF	FE	XOR8
(Xingkechuang default)	62	39	09	FF	FF	FF	FF	FD	XOR8
Successfully returned	62	39	09	00	00	00	00	66	XOR8

The data bit is 0xffff for the factory restoration command, the factory restoration command carries the parameter FE or FD, and the parameter write response bit:
Parameter Description:
FE: Restore the default configuration of Xingkechuang
FD: restore user default configuration
The above command restores the factory with the address of 0000. If you want to restore the factory with any address, you can change the address to FF, FF, as shown below:
62 39 09 FF FF FF FF FE
62 39 09 FF FF FF FF FD

Write address	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B2)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	62	32	09	FF	FF	00	01	00	XOR
Successfully returned	62	32	09	00	00	00	00	66	XOR8
Parameter description: 0~65534 The above command changes the 0x0000 address to 0x0001									

Modify the baud rate	Data Format

	1	2	3	4	5	6	7	8	9
	Command (B0)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	62	30	09	FF	FF	00	02	00	XOR
Successfully returned	62	30	09	00	00	00	00	66	XOR8

Parameter Description:
0 = 2400bps
1 = 4800bps
2 = 9600bps
3 = 14400bps
4 = 19200bps
5 = 38400bps
6 = 56000bps
7 = 57600bps
8 = 115200bps
9 = 128000bps
The above command changes the baud rate to 9600bps

Revise	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B4)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
Upload mode	62	34	09	FF	FF	00	01	00	XOR
Successfully returned	62	34	09	00	00	00	00	66	XOR

Parameter Description:
0: Manual query mode
1: Automatic serialization mode
The above command changes the upload mode to: (automatic upload mode)

Modify automatically	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B5)		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
Upload interval	62	35	09	FF	FF	00	01	00	XOR

| Successfully returned | 62 | 35 | 09 | 00 | 00 | 00 | 00 | 66 | XOR |

Parameter description: 1-100 (corresponding to 100ms-10s)
The above command will modify the automatic upload interval to 100ms

Revise LED mode	Data Format								
	1	2	3	4	5	6	7	8	9
	Command (B7)	Data length		Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	62	37	09	FF	FF	00	01	00	XOR
Successfully returned	62	37	09	00	00	00	00	66	XOR

Parameter Description:
0 = lights up when inductive
1 = Turn off when sensing
2 = always off
3 = always on
The above command changes the LED mode to: (1 = off when inductive)

Modify the relay mode	Data format								
	1	2	3	4	5	6	7	8	9
	Command (B8)	Data length		Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	62	38	09	FF	FF	00	01	00	XOR
Successfully returned	62	38	09	00	00	00	00	66	XOR

Parameter Description:
0 = Start when sensed
1 = Turn off when sensing
The above command changes the relay mode to: (1 = close when there is induction)

Revise Line mode	Data format								
	1	2	3	4	5	6	7	8	9
	Command	Data		Address	Address	Data high	Data Low	Answer	Check (XOR8)

	(a0)	length	high	Low				
send command	61	30	09	FF	FF	00	01	00	XOR
Successfully returned	62	30	09	00	00	00	00	66	XOR

Parameter Description:
0 = Relay mode
1 = UART mode
The above command changes the line mode to: (1 = UART mode)

Revise Trailing mode	Data format								
	1	2	3	4	5	6	7	8	9
	Command (a2	Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	61	32	09	FF	FF	00	01	00	XOR
Successfully returned	62	32	09	00	00	00	00	66	XOR

Parameter description: (see the trailing configuration table for details)
0 = high precision
1 = normal
2 = high stability
The above command will modify the trailing mode to: (1 = normal)

Read Current configuration (String)	Data format								
	1	2	3	4	5	6	7	8	9
	Command (d1	Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	64	31	09	FF	FF	00	00	00	XOR
Successfully returned	Current configuration string								

Parameter Description:
Baud rate 0-9, 2400bps-128000bps (see the baud rate configuration table for details)
Device address 0-65534 (65535 is the broadcast address)
Calibration distance value 30-2000 (30-2000mm)
Upload mode 0=automatic upload, 1=manual query
Upload interval Value range 1-100 (corresponding to 100ms-10s)

LED mode 0=light on when there is induction, 1=off when there is induction, 2=normally off, 3=normally on
Relay mode 0=start when there is induction, 1=close when there is induction
Line output mode 0=relay mode, 1=UART mode

Read current configuration (Hex)	Data format								
	1	2	3	4	5	6	7	8	9
	Command (b1		Data length	Address high	Address Low	Data high	Data Low	Answer	Check (XOR8)
send command	62	31	09	FF	FF	00	00	00	XOR

Successfully returned	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29
	command		length	Address		Reserve					Reserve	No calibration	Baudrate	Device address		Calibration distance value		Upload mode	Uploading interval	Reserve		LED-mode	Relay mode	Line output mode	Reserve	Reserve	Reserve	Answer	Check
	62	31	1D	00	00						FF	02	00	00	00	64	00	0A			00	00	00					66	XOR

12th. Troubleshooting guide

problem	LED indication	handle
Output short circuit	Flash	Check that the output current is not more than 1A
Product failure	Pulse flash	Contact the agent to return
Mode setting error	Always on Always off Output reverse	Check the LED mode and relay mode. If it is not normal after restoring to the factory, please contact the agent to return it.

13th. Precautions for use

1. The receiving device is interfered by strong light (normal indoor light is not affected, when the light is too strong, the sensitivity will be reduced and the distance will become closer). When installing, try to avoid strong light directly on the probe to make the sensing distance closer and affect the function.
2. When installing, avoid working in an environment with high dust concentration (because high

concentration dust is equivalent to sensing objects, which will cause the sensor to malfunction) to avoid misoperation.

14th.Product warranty terms and instructions

(A) .Warranty service

1. Warranty period maintenance: from the date of purchase, the product host has a one-year free warranty. The company has the right to decide to repair or replace the faulty part. If it is replaced, the replacement part may be a new device or a repair product of the same category, function, and quality. The replaced faulty part belongs to the company; the product Resale and repair do not affect the warranty period. Products that have been repaired or replaced continue to enjoy the original remaining warranty period service. If the warranty period is less than three months after the repair, the repaired or replaced part shall be shipped from the date of delivery Warranty for three months; all products of the company are guaranteed for repair.

2. Loss upon arrival (DOA) replacement: From the day of purchase, you can enjoy a free replacement service within 7 days. Products with the following problems are defined as DOA equipment: the packing and packing list do not match after the first unpacking of the product; some or all of the components cannot be used normally after the first unpacking of the product (surface scratches or other things that do not affect the function of the device) Defects are not included); other hardware failures identified by our company's engineers remotely or locally.

(B). Applicable limitations of warranty

For the following situations, the company does not assume warranty responsibility:

1. The product is out of warranty; the surface of the product is fragile and damaged; the appearance of the product is seriously damaged, installation/use in abnormal environment, unauthorized disassembly and repair/modification, external power supply damage and other abnormal damage;

2. Damage caused by incorrect installation and use of the product by the user not following the requirements of the manual;

3. Damage caused by natural disasters and human negligence (fire, lightning, flooding, impact, etc.).

(C) .Accessories and consumables are not covered by the warranty.

(D) .Non-free warranty service

Within two years of product purchase, for non-warranty product (including components) failures and damages, you can choose paid maintenance services (free labor costs), and we will charge the transportation cost of repairing parts and accessories according to the actual situation.

(E). Ways to obtain warranty service

It is recommended that you contact the dealer who purchased this product to obtain the warranty service. For the warranty, please present a valid warranty card (the dealer's stamp is required to take effect) or the purchase invoice/receipt: if you can't show it, the product's free warranty period 12 months from the product shipment date, and the latest DOA application deadline is 7 days from the product shipment date.

(F). Statement

1. The copyright of this manual belongs to Shenzhen Xingkechuang Technology Co., Ltd. (Xingkechuang) and its authorized licensors. Shenzhen Xingkechuang Technology Co., Ltd. (Xingkechuang) reserves all rights.

2. Without the written permission of the company, no unit or individual may excerpt or copy part or all of the contents of this manual, and shall not spread it in any form.

3. The customer recognizes that the purpose of the design and production of the company's products does not involve use in products related to life support or other systems or products used in other dangerous activities or environments. Personal injury or death, property or environmental damage due to product failure (collectively referred to as high-risk activities). The company's products are artificially used in high-risk activities, and the company does not guarantee it and is not liable to customers or third parties.

4. Due to product version upgrades or other reasons, the contents of this manual may change. Xingkechuang reserves the right to modify the contents of this manual without any notice or prompt. This manual is only used as a guide. Xingkechuang makes every effort to provide accurate information in this manual. However, Xingkechuang does not guarantee that the contents of the manual are completely free of errors. All statements, information and suggestions in this manual do not constitute any express or Implied guarantee.

5. Not all models are available in all countries/regions

Please keep this manual properly. Before using the product, please read this manual carefully. When using the product, please be sure to operate in accordance with this manual. The company is not responsible for injuries and accidents caused by operations that do not follow this manual.

(G).Environmental protection This product meets the design requirements for environmental protection.The storage, use and disposal should comply with relevant national laws and regulations.Seek to proceed.

15th. Manual version

Version	Release date
V10	March 28, 2023